

# Extended Local Volatility Modeling

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To appear in  
*Annals of Applied Probability*

School of Mathematics  
University of Minnesota  
March 29, 2013

# Outline

- ▶ Markov projection (Krylov/Gyöngy)
- ▶ First application: Index options
- ▶ Second application: Mixture models
- ▶ Extension of Markov projection
- ▶ Main result

# Markov projection

Theorem (Gyöngy (1986); see also Krylov (1984))

Suppose

$$dX(t) = \mu_t dt + \sigma_t dW(t),$$

where  $\mu_t$  and  $\sigma_t$  are adapted random processes and  $W(t)$  is a Brownian motion. Define (nonrandom) functions

$$\hat{\mu}(t, x) = \mathbb{E}[\mu_t | X(t) = x], \quad \hat{\sigma}(t, x) = \left( \mathbb{E}[\sigma_t^2 | X(t) = x] \right)^{1/2}.$$

Then there exists a solution of the stochastic differential equation

$$dY(t) = \hat{\mu}(t, Y(t)) dt + \hat{\sigma}(t, Y(t)) dW(t)$$

with initial condition  $Y(0) = X(0)$  such that at each fixed time  $t$ ,  $Y(t) \stackrel{\mathcal{D}}{=} X(t)$ .

## Comments on Gyöngy's Theorem

- ▶ When the stochastic differential equation for  $Y$  has a unique solution, this solution is Markov.  $Y$  is called the **Markov projection** of  $X$ .
- ▶ Within the context of finance,  $\hat{\sigma}(t, x)$  is the **local volatility surface** of Dupire.
- ▶ Because  $Y(t) \stackrel{\mathcal{D}}{=} X(t)$  for each fixed  $t$ , **European calls** on  $X$  have the same prices as the corresponding calls on  $Y$ .
- ▶ **Path-dependent options** on  $X$  do **not** have the same prices as the corresponding path-dependent options on  $Y$ .
- ▶ Gyöngy's Markov projection theorem requires that  $\sigma_t$  is **uniformly bounded away from zero** and from above, and hence  $\hat{\sigma}(t, x)$  is uniformly bounded away from zero and from above.
- ▶ Within the context of finance, Gyöngy **does not apply** to many stochastic volatility models, e.g., Heston.

## First application of Markov projection: Index options

- ▶ Individual stocks:  $dS_i(t) = \sigma_i S_i(t) dW_i(t)$ ,  $i = 1, \dots, n$
- ▶ Index:  $S(t) = \sum_{i=1}^n w_i S_i(t)$
- ▶ Evolution of index:  $dS(t) = \sum_{i=1}^n w_i \sigma_i S_i(t) dW_i(t)$
- ▶ Markov projection:

$$\hat{\sigma}(t, s) = \left( \mathbb{E} \left[ \sum_{i,j=1}^n w_i w_j \rho_{ij} \sigma_i \sigma_j S_i(t) S_j(t) \mid S(t) = s \right] \right)^{1/2}$$

- ▶ Local volatility model for index:

$$dS^{\ell v}(t) = \hat{\sigma}(t, S^{\ell v}(t)) dW(t)$$

- ▶ **European calls** on  $S$  have the same prices as European calls on  $S^{\ell v}$ .
- ▶ See Piterbarg, "Markovian projection for volatility calibration," *Risk* 20(4), 2007, for an **approximation** of the local volatility surface.

## Second application of Markov projection: Mixture models

The Black-Scholes model assumes that the underlying asset price has a **log-normal distribution** under a risk-neutral probability measure at the option expiration date  $T$ . It has been proposed to instead assume that the distribution is a **mixture of log-normals**.

- ▶ **Empirical reason:** Mixture of two log-normals fits the volatility smile.
- ▶ **Computational reason:** The mixture of log-normals gives prices and Greeks that are mixtures of Black-Scholes prices and Greeks.

## A mixture of models is not a model.

A model describes the **evolution** of the underlying asset price, not just its risk-neutral distribution at the final time  $T$ .

- ▶ If we don't model the evolution, we cannot build successful trading strategies. Trading strategies generate profits and losses **over time**.
- ▶ If we don't model the evolution, we cannot price **path-dependent options**. The price of a path-dependent option depends on the joint distribution of the underlying asset at multiple time points.

## A naive mixture model

Assume

$$0 < v_1 < v_2.$$

Consider a “model” with

$$dS_t = \sigma_0 S_t dW_t, \quad 0 \leq t \leq T,$$

where

$$\mathbb{P}\{\sigma_0^2 = v_1\} = \frac{1}{2}, \quad \mathbb{P}\{\sigma_0^2 = v_2\} = \frac{1}{2}.$$

We set the value of  $\sigma_0$  at time zero, and then the risk-neutral distribution of  $S(T)$  is a mixture of log-normals with volatilities  $\sqrt{v_1}$  and  $\sqrt{v_2}$ .

Immediately after time zero, we can determine  $\sigma_0$  from the observed returns, and we no longer have a mixture model.



## A less naive mixture model

At time 0 choose a volatility  $\sigma_0$  with

$$\mathbb{P}\{\sigma_0^2 = v_1\} = \frac{1}{2}, \quad \mathbb{P}\{\sigma_0^2 = v_2\} = \frac{1}{2}.$$

Use this volatility throughout to obtain a process  $S$ .

Choose a time-partition

$$\Pi : 0 = T_0 < T_1 < T_2 < \dots < T_n = T.$$

At each time  $T_i$ , compute

$$p_1(T_i, s) = \mathbb{P}\{\sigma_0^2 = v_1 | S_{T_i} = s\}, \quad p_2(T_i, s) = \mathbb{P}\{\sigma_0^2 = v_2 | S_{T_i} = s\}.$$

Construct a second process  $S^\Pi$  recursively. On  $[T_0, T_1)$  use the volatility  $\sigma_0$  chosen above. At each subsequent time  $T_i$ , **redraw the volatility according** to

$$\mathbb{P}\{(\sigma_{T_i}^\Pi)^2 = v_1\} = p_1(T_i, S_{T_i}^\Pi), \quad \mathbb{P}\{(\sigma_{T_i}^\Pi)^2 = v_2\} = p_2(T_i, S_{T_i}^\Pi),$$

and use it on  $[T_i, T_{i+1})$ .

## Relationship between $S$ and $S^\Pi$

- ▶ We set  $\sigma_0^\Pi = \sigma_0$ .
- ▶ We use volatility  $\sigma_0$  to generate  $S_t$ ,  $0 \leq t \leq T_1$ .
- ▶ We use volatility  $\sigma_0^\Pi$  to generate  $S_t^\Pi$ ,  $0 \leq t \leq T_1$ .
- ▶ Therefore,  $S_t = S_t^\Pi$  for  $0 \leq t \leq T_1$ .
- ▶ At time  $T_1$ , we choose a new  $\sigma_{T_1}^\Pi$  so that
$$(S_{T_1}, \sigma_0) \stackrel{\mathcal{D}}{=} (S_{T_1}^\Pi, \sigma_{T_1}^\Pi).$$
- ▶ We use volatility  $\sigma_{T_1}^\Pi$  to continue  $S_t^\Pi$ ,  $T_1 \leq t \leq T_2$ .
- ▶ Therefore,  $(S_t, \sigma_0) \stackrel{\mathcal{D}}{=} (S_t^\Pi, \sigma_t^\Pi)$ ,  $T_1 \leq t \leq T_2$ .
- ▶ At time  $T_2$ , we choose a new  $\sigma_{T_2}^\Pi$  so that
$$(S_{T_2}, \sigma_0) \stackrel{\mathcal{D}}{=} (S_{T_2}^\Pi, \sigma_{T_2}^\Pi).$$
- ▶ We use volatility  $\sigma_{T_2}^\Pi$  to continue  $S_t^\Pi$ ,  $T_2 \leq t \leq T_3$ .
- ▶ Therefore,  $(S_t, \sigma_0) \stackrel{\mathcal{D}}{=} (S_t^\Pi, \sigma_t^\Pi)$ ,  $T_2 \leq t \leq T_3$ .

# Properties of $S^\Pi$

- ▶ For each fixed  $t$ ,  $S_t \stackrel{\mathcal{D}}{=} S_t^\Pi$ , and so . . .
- ▶ **European calls** on  $S$  have the same prices as European calls on  $S^\Pi$ .
- ▶  $S^\Pi$  has **piecewise constant volatility**.
- ▶ Immediately after each  $T_i$ , observation of  $S^\Pi$  reveals the volatility being used on  $[T_i, T_{i+1})$ , but not the volatilities that will be used after time  $T_{i+1}$ .

## A local volatility model as the limit

Recall

$$0 = T_0 < T_1 < T_2 < \cdots < T_n = T.$$

Let  $n \rightarrow \infty$  so that  $\max_i |T_{i+1} - T_i| \rightarrow 0$ .

$S^\Pi$  converges to a process  $S^{\ell v}$  satisfying

$$dS_t^{\ell v} = \hat{\sigma}(t, S_t^{\ell v}) S_t^{\ell v} dW_t, \quad 0 \leq t \leq T,$$

where

$$\hat{\sigma}(t, s) = \left( \mathbb{E}[\sigma_0^2 | S_t = s] \right)^{1/2} = \left( \frac{v_1 \pi_1(t, s) + v_2 \pi_2(t, s)}{\pi_1(t, s) + \pi_2(t, s)} \right)^{1/2}$$

and  $\pi_i(t, s)$  is the log-normal distribution corresponding to time  $t$  and volatility  $\sqrt{v_i}$ .

## Comments

- ▶ This formula for the **local volatility surface for a mixture model** was worked out by Brigo and Mercurio, “A mixed-up smile,” *Risk*, September 2000.
- ▶ The formula is a special case of Gyöngy’s Markov projection theorem.
- ▶ The derivation of the formula given here provides a **new proof technique** that allows us to remove Gyöngy’s conditions that the diffusion coefficient must be uniformly bounded away from zero and bounded from above.

# Extensions of Markov projection

## Corollary (of the Main Result)

Assume

$$dS_t = \sigma_t S_t dW_t, \quad 0 \leq t \leq T,$$

where  $\sigma_t$  is a random process. Define

$$M_t \triangleq \max_{0 \leq u \leq t} S_u.$$

Then there exists a “local volatility” function  $\hat{\sigma}(t, s, m)$  and there exists a solution of the stochastic differential equation

$$dS_t^{\ell v} = \hat{\sigma}(t, S_t^{\ell v}, M_t^{\ell v}) S_t^{\ell v} dW_t,$$

where

$$M_t^{\ell v} \triangleq \max_{0 \leq u \leq t} S_u^{\ell v},$$

such that for each fixed  $t \geq 0$ , we have  $(S_t^{\ell v}, M_t^{\ell v}) \stackrel{\mathcal{D}}{=} (S_t, M_t)$ .

## Comments on extended Markov projection

- ▶ The **extended local volatility surface** is

$$\hat{\sigma}(t, s, m) = \left( \mathbb{E}[\sigma_t^2 | \mathcal{S}_t = s, M_t = m] \right)^{1/2}.$$

- ▶ There are versions of the corollary for the **minimum stock price**, the **average stock price**, and combinations of these, so ....
- ▶ the corollary applies to **path-dependent options** whose payoff depends on the maximum, minimum or average stock price, e.g., barrier and Asian options.
- ▶ The proof follows the approach outlined for the mixture model.
- ▶ Disclaimer: We need to assume that  $\sigma_t$  is bounded away from zero in order to guarantee that the local volatility stochastic differential equation has a **unique solution**.

## Example of nonuniqueness

Let  $X_0 = 0$  and  $dX(t) = \sigma_t dW_t$ , where

$$\sigma_t = I_{(1,\infty)}(t)I_{\{W_1 > 0\}}.$$

The solution is

$$X_t = I_{(1,\infty)}(t)I_{\{W_1 > 0\}}(W_t - W_1).$$

We have  $\hat{\sigma}(t, x) = 0$  for  $0 \leq t \leq 1$ , and for  $t > 1$ ,

$$\hat{\sigma}^2(t, x) = \mathbb{E}[\sigma_t^2 | X_t = x] = \begin{cases} 1, & \text{if } x \neq 0, \\ 0, & \text{if } x = 0. \end{cases}$$

Both  $X_t^{(1)} \equiv 0$  and

$$X^{(2)}(t) = I_{(1,\infty)}(t)(W_t - W_1)$$

are solutions of  $dX_t^{\ell v} = \hat{\sigma}(t, X_t^{\ell v})dW_t$ . The solution we want is  $X^{(1)}$  with probability  $\frac{1}{2}$  and  $X^{(2)}$  with probability  $\frac{1}{2}$ .



# The Main Result

Let  $C^d$  denote the space of continuous functions from  $[0, \infty)$  to  $\mathbb{R}^d$ .

Define three operators mapping  $C^d \times [0, \infty)$  to  $C^d$ :

- ▶ Shift operator:  $\Theta(x, t) \triangleq x(t + \cdot)$ ,
- ▶ Stopping operator:  $\nabla(x, t) \triangleq x(t \wedge \cdot)$ ,
- ▶ Difference operator:  $\Delta(x, t) \triangleq x(t + \cdot) - x(t)$ .

We say  $\Phi: C^d \rightarrow C^d$  is an **updating function** if

- ▶ Initiation:  $\Phi_0(x) = x(0)$ ,
- ▶ Non-anticipativity:  $\nabla(\Phi(x), t) = \nabla(\Phi(\nabla(x, t)), t)$ ,
- ▶ “Markov” property:  $\Theta(\Phi(x), t) = \Phi(\Phi_t(x) + \Delta(x, t))$ .

## Theorem

Given

$$X_t = X_0 + \int_0^t \mu_s ds + \int_0^t \sigma_s dW_s, \quad t \geq 0,$$

where  $\mathbb{E} \int_0^t (\|\mu_s\| + \|\sigma_s \sigma_s^T\|) ds < \infty$  for all  $t \geq 0$ . Let  $Z = \Phi(X)$ .  
For Lebesgue-almost-every  $t$ , there are versions

$$\hat{\mu}(t, Z_t) = \mathbb{E}[\mu_t | Z_t], \quad \hat{\sigma}(t, Z_t) \hat{\sigma}^T(t, Z_t) = \mathbb{E}[\sigma_t \sigma_t^T | Z_t],$$

and a weak solution

$$\begin{aligned} \hat{X}_t &= \hat{X}_0 + \int_0^t \hat{\mu}(s, \hat{Z}_s) ds + \int_0^t \hat{\sigma}(s, \hat{Z}_s) dW_s, \\ \hat{Z} &= \Phi(\hat{X}), \end{aligned}$$

such that  $\hat{Z}_t \stackrel{D}{=} Z_t$  for every  $t \geq 0$ .