

Semester as progression to Stokes' theorem:  $X \subseteq M$  compact, good boundary

then  $\int_{\partial X} \varphi = \int_X d\varphi$ ,  $\varphi$ : class  $C^2$ -form (k-1 if  $\dim(M)=k$ ) on  $X$

① integration using Riemann sums  
(dyadic pairings of compactly supp. functions)  
with compact values.

- 3 key results:
- (a) integrability (iff discontinuous on a set of measure 0.)
  - (b) Fubini's thm (iterated integration)
  - (c) Change of vars. theorem

lots of hypotheses, on change of vars function  $\Phi$

(injective on  $X - \partial X$ ,  
 $C^1$  with Lipschitz deriv.

$D\Phi$  invertible at all  $x \in X - \partial X$ .)

1/2 step to Lebesgue integrability

Infinite sums of Riemann integrable functions.

- 4 ~~X~~ key results:
- (a) well definedness
  - (b) dominated convergence theorem
  - (c/d) Fubini's thm, change of vars.

L-int. functions

$f_k \rightarrow f$ , and  $\exists$  L-int.  $F$  s.t.  $|f_k(x)| \leq F(x)$  a.e.

then  $f$  is integrable and equal to  $\lim_k \int f_k$ .

(leads to diff. under integral sign.)

So now can integrate more general functions (not nec. compact support, compact values)

② integration on manifolds.

two key topics: (a) relaxed parametrizations

(b) curvature.

$U \subseteq \mathbb{R}^n$  with "bad piece  $X$ "

$\gamma(U) = M = \gamma(U-X)$

like before: one-one

$C^1$  w/ Lipschitz deriv. (loc.)

$D\gamma$  one-one  $\forall u \in U-X$

$k$ -volume of  $X$

and  $\gamma(X) \cap$  compact  
 $= 0 \quad \forall$  compact.

Lipschitz if function is  $C^2$  (even had way of producing Lipschitz ~~ratio~~ ratio from second partials (long time ago))

Gauss' theorem on area of disc on surface.

(error given by curvature)

$$\text{Area}(D_r(p)) = \pi r^2 - \frac{\pi K(p)}{2} r^4 + o(r^4)$$

Make this our pf.

(Each chapter has important "independence of param" using change of vars but won't pick it each time)

③ Oriented integration on manifolds. (~40% of test)

- differential forms (and form fields) (evaluate them, take exterior deriv, simple properties)

- Stokes' theorem

(pf. is one for domain nice w.r.t coordinate axes)

Prop. 6.9.7.

- orientations (definition + key examples (use form to make orientation)),

consistent with param:

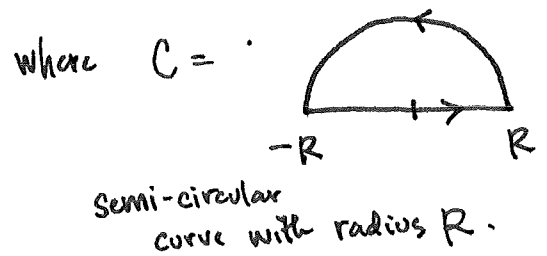
- "Favorite forms"

- integrating  $k$ -forms over parametrized domain

$$\Omega ( D\gamma(u) ) = 1 \quad \forall u \in U-X$$

$$\gamma: U \rightarrow M.$$

Example:  $\int_C xy \, dy + x^3 \, dx$



Parametrize each piece. Or use Stokes' theorem in  $\mathbb{R}^2$ .

Take  $d(f \, dx + g \, dy)$  to make 2-form. In general, only

$$d_y f \, dy \wedge dx + d_x g \, dx \wedge dy \text{ survive}$$

$$= (D_x g - D_y f) \, dx \wedge dy.$$

In  $\mathbb{R}^2$ , identity:

$$\int_C f \, dx + g \, dy =$$

Green's/Stokes' thm  $\Rightarrow$

$$\int_C xy \, dy + x^3 \, dx = \int_{S=\text{semi-circle}} y \, dx \wedge dy.$$

$$\int_S (D_x g - D_y f) \, dx \wedge dy.$$

(with  $\partial S = C$ )

is called "Green's Theorem"

$\stackrel{=}{\text{POLAR!}}$

$$\int_0^\pi \int_0^R r \sin \theta \, r \, dr \, d\theta = \frac{R^3}{3} \cdot [-\cos \theta] \Big|_0^\pi = \boxed{2R^3/3}$$

A little bit fast about checking that param. using polar coords was consistent with orientation.

$$\Omega(D\gamma(u)) = 1 \quad \forall u \in [0, \pi) \times (0, R).$$

in  $\mathbb{R}^2$ , if we have open set, can use  $x, y$  as coords. on manifold.

$$dx \wedge dy = |d^2(x, y)|$$

One more example: Compute the flux through the unit cube

of the vector field  $\mathbb{F}(x,y,z) = \begin{bmatrix} xy^2 + z \\ 4yz - xz \\ x \cos y \end{bmatrix}$

with standard orientation on cube.

Again, Stokes' theorem:

(outward pointing normal)

(nice to remember that flux form

$d: \mathbb{F}(x,y,z) \mapsto \text{Mass form } M \underbrace{\text{div}(\mathbb{F})}_{\nabla \cdot \mathbb{F}}$ )

2-form we get from  $\det \begin{bmatrix} F & v & w \\ \mathbb{F} & \downarrow & \downarrow \\ | & | & | \end{bmatrix}$

vector field assoc. to  $\mathbb{F}$

then

$$\int_{\partial C} \mathbb{F} = \int_C d\mathbb{F} = \int_C M \text{div}(\mathbb{F})$$

"divergence theorem"

claim:  $\mathbb{F}_{\mathbb{F}}(\underline{x})(\underline{v}, \underline{w}) = \underbrace{F(\underline{x}) \cdot N(\underline{x})}_{\text{unit normal vector}} |d^2 \underline{x}|$

$$\begin{aligned} & (N(\underline{x}) |d^2 \underline{x}| (\underline{v}, \underline{w})) \\ &= N(\underline{x}) \cdot |\underline{v} \times \underline{w}| \\ &= \underline{v} \times \underline{w} \end{aligned}$$

so just check that  $F(\underline{x}) \cdot (\underline{v} \times \underline{w}) = \det \begin{pmatrix} F & v & w \\ | & | & | \end{pmatrix}$ .

$$= \int_C (xy^2 + 4z) dx dy dz$$

$$= \int_0^1 \left. \frac{1}{3} y^3 + 4yz \right|_0^1 dz$$

$$= \int_0^1 \left( \frac{1}{3} + 4z \right) dz$$

$$= \frac{1}{3} + 2 = \boxed{\frac{7}{3}}$$