

Definition: A vector field is called "rotation-free" if $\text{curl}(\vec{F}) = \underline{0}$.

and "incompressible" if $\text{div}(\vec{F}) = \underline{0}$.

check the following properties (consequences of fact that $d(d\varphi) = 0$ or just check directly...)

① $\text{curl}(\text{grad}(f)) = 0$

② $\text{div}(\text{curl}(F)) = 0$

Example: a magnetic field is always expressible as $\text{curl}(\vec{A})$ for some vector field \vec{A} . Thus, magnetic field is always incompressible.

Examples of Stokes' theorem : $X = M : k\text{-manifold} \subset \mathbb{R}^n$, $\varphi : k-1\text{-form}$
 compact, "good" boundary

then
$$\int_{\partial X} \varphi = \int_X d\varphi.$$

Easy example : $X = \text{rectangle in } \mathbb{R}^2$. Then $\int_{\partial X} \varphi$, $\varphi : 1\text{-form}$
 say with vertices $(0,0), (a,0), (a,b), (0,b)$

is painful as # of sides in boundary is $2n = 4$. (worse in higher dimensions)

Pick $\varphi : x dy - dx$

$$d\varphi = d(x dy - dx) = dx \wedge dy - d(dx) = \underbrace{dx \wedge dy}_{\text{volume form on } \mathbb{R}^2}.$$

so by Stokes' thm.

$$\int_{\partial X} \varphi = \int_X d\varphi = \int_{\text{rect. } X} dx \wedge dy = a \cdot b.$$

expand this:

γ : param. of rectangle.

Harder example over cube in \mathbb{R}^3 ,
 integrating 2-form over boundary
 of cube.

$$\int_{\partial M} \det(D\gamma(u)) |d^k \underline{u}| = \int_M |d^k \underline{x}|.$$

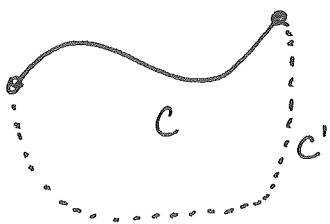
or can pick "trivial param"

$$\gamma : \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \mapsto \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

$(u_1, u_2) \in \text{Rectangle.}$

Even if want to integrate over $(k-1)$ -manifold not a boundary, still

play tricks: e.g. want to integrate over C , complete it to boundary of 2-manifold using C' , where



C' simple enough.

$$C \cup C' = \partial X$$

X : "good" 2-manifold

Stokes' theorem gives
$$\int_{\partial X} \varphi = \int_X d\varphi$$

So
$$\int_C \varphi = \int_X d\varphi - \int_{C'} \varphi.$$

For example, if $d\varphi = 0$

then
$$\int_C \varphi = - \int_{C'} \varphi$$

e.g. $\varphi = x dy + y dx$

then $d\varphi = dx \wedge dy + dy \wedge dx = 0.$

(pick 0-form f , then df is 1-form and $d(df) = 0$)

$f = xy$ then $df = dx \cdot y + dy \cdot x.$

C' any curve with same endpoints.

(C' nice enough)

Earlier sketch of Stokes' theorem:

$$\int_X d\varphi \approx \sum_{i=1}^N d\varphi(P_i)$$

assume φ constant on small P_i

$$\approx \sum_{i=1}^N \int_{\partial P_i} \varphi \approx \int_{\partial X} \varphi$$

definition of d as flux.

orientations on boundaries cancel.

Works nicely if boundary of X is well-approximated by dyadic pairing.