

Exploring consequences of definition of derivative: $Df(\underline{a})$: linear trans

such that $\lim_{\underline{h} \rightarrow \underline{0}} \frac{f(\underline{a} + \underline{h}) - f(\underline{a}) - Df(\underline{a})(\underline{h})}{|\underline{h}|} = \underline{0}$.

Think of numerator as describing whether $f(\underline{a}) + Df(\underline{a}) \cdot \underline{h}$ is a good linear approximation to $f(\underline{a} + \underline{h})$.

If one-variable f with power series rep'n, then we'd subtract constant, linear terms, leaving quadratic and higher, so indeed limit is $\underline{0}$.

Prove that differentiable \Rightarrow continuous.

Directional derivatives

Properties of derivatives

(1) Derivatives of constant function = 0 matrix

(2) Derivative of linear function is function (i.e. matrix of its linear transformation)

(3) Derivative of f exists at \underline{a}

\Leftrightarrow Derivative of $f^{(i)}$ $i=1, \dots, m$ exist at \underline{a}

then $Df(\underline{a})\underline{v} = \begin{bmatrix} Df^{(1)}(\underline{a})\underline{v} \\ \vdots \\ Df^{(m)}(\underline{a})\underline{v} \end{bmatrix}$

(4) sums, product of \mathbb{R} -valued and \mathbb{R}^m valued, dot products

(5) all polynomials, rational functions w/ non-vanishing denom are differentiable

Additional remarks:

① We obtain lots of properties of derivatives from properties of limits
e.g. sums, products, composition,
 f differentiable $\Leftrightarrow f^{(i)}$ differentiable for $i=1, \dots, m$.

② Can compute directional derivatives - viewed as generalization of partial derivatives, now not along coordinate axis but along a vector.

Define $D_{\underline{v}} f(\underline{a}) \stackrel{\text{def}}{=} \lim_{t \rightarrow 0} \frac{f(\underline{a} + t\underline{v}) - f(\underline{a})}{t}$ (here t is a scalar in \mathbb{R})

Proposition: If f is differentiable at \underline{a} , then

$$D_{\underline{v}} f(\underline{a}) = Df(\underline{a}) \cdot \underline{v}$$

Jacobien matrix mult. vector \underline{v}

pf: Check for $t \rightarrow 0^+$. Let you check $t \rightarrow 0^-$. (just as easy)

then $\lim_{t \rightarrow 0^+} \frac{f(\underline{a} + t\underline{v}) - f(\underline{a}) - \cancel{Df(\underline{a}) \cdot (t\underline{v})} Df(\underline{a}) \cdot (t\underline{v})}{t} = \underline{0}$

since f diff. at \underline{a} . But $Df(\underline{a})$ is linear so

$$Df(\underline{a})(t\underline{v}) = t \cdot Df(\underline{a})(\underline{v}) \Rightarrow$$

$$D_{\underline{v}} f(\underline{a}) = \lim_{t \rightarrow 0^+} \frac{f(\underline{a} + t\underline{v}) - f(\underline{a})}{t} = Df(\underline{a}) \underline{v}. \checkmark$$

proof that derivative of linear map is itself:

cute idea: use uniqueness of $Df(\underline{a})$.

Indeed, f is linear so $\lim_{\underline{h} \rightarrow \underline{0}} \frac{f(\underline{a} + \underline{h}) - f(\underline{a}) - f(\underline{h})}{|\underline{h}|} = \underline{0}$

because numerator is identically 0. //

other proofs of derivative laws amount to clever manipulation of

difference quotient (e.g. add + subtract the same term to allow
regrouping + factoring)

and resemble their

one-variable counterparts.

chain rule: $g: U \rightarrow V$ $U \subseteq \mathbb{R}^n, V \subseteq \mathbb{R}^m$

$f: V \rightarrow \mathbb{R}^p$ so $f \circ g$ defined.

Suppose g diff. at \underline{a} , f diff. at $g(\underline{a})$ then

$f \circ g$ diff. at \underline{a} with derivative $D(f \circ g)(\underline{a}) =$

$$Df(g(\underline{a})) \circ Dg(\underline{a})$$

↑
Composition of
linear transformations
(matrix mult.)

pf. of chain rule: Kind of messy...

example: $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} x^2 - y^2 \\ 2xy \end{bmatrix}$$

$g: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\begin{bmatrix} u \\ v \end{bmatrix} \mapsto \begin{bmatrix} u \cos v \\ u \sin v \end{bmatrix}$$

$$D(f \circ g) \begin{bmatrix} u \\ v \end{bmatrix} \stackrel{\text{Chain Rule}}{=} Df(g \begin{bmatrix} u \\ v \end{bmatrix}) \cdot Dg \begin{bmatrix} u \\ v \end{bmatrix}$$

$$g \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} u \cos v \\ u \sin v \end{bmatrix} \quad \text{and} \quad Df = \begin{bmatrix} 2x & -2y \\ 2y & 2x \end{bmatrix}$$

$$\text{so } Df(g \begin{bmatrix} u \\ v \end{bmatrix}) = \begin{bmatrix} 2u \cos v & -2u \sin v \\ 2u \sin v & 2u \cos v \end{bmatrix}$$

$$Dg = \begin{bmatrix} \cos v & -u \sin v \\ \sin v & u \cos v \end{bmatrix} \quad \text{Now do matrix mult.}$$

(can also just write composition explicitly and take Jacobian.)

$$f \circ g \begin{bmatrix} u \\ v \end{bmatrix} = f \begin{bmatrix} u \cos v \\ u \sin v \end{bmatrix} \stackrel{\text{using trig ident.}}{=} \begin{bmatrix} u^2 \cos 2v \\ u^2 \sin 2v \end{bmatrix}$$

Check they
are the
same.