

Last week: studying differential forms. Maps:

$$\underbrace{\Omega_S^0}_{\text{functions}} \xrightarrow{d} \underbrace{\Omega_S^1}_{\substack{\text{1-forms} \\ \text{maps from } S \text{ to} \\ \text{(cotangent space)}}} \xrightarrow{d} \underbrace{\Omega_S^2}_{\substack{\text{2-forms} \\ \text{maps from } S \text{ to} \\ \text{(bilinear forms} \\ \text{on cotangent} \\ \text{space)}}}$$

$$f \xrightarrow{d} d(f) = \frac{\partial f}{\partial x_1} dx_1 + \frac{\partial f}{\partial x_2} dx_2$$

$$d = dx_1 + dx_2 \xrightarrow{d} \left(\frac{\partial dx_2}{\partial x_1} - \frac{\partial dx_1}{\partial x_2} \right) dx_1 \wedge dx_2$$

quantity appearing
in Green's thm.

Exploring question, in \mathbb{R}^2 , of whether $\exists f$ s.t. $d(f) = \alpha$ for any 1-form α .

Ans. (Green's thm) Yes, if and only if $d(\alpha) = 0$ "closed form"

In general, for ~~manifold~~ surface S , this is more complicated. Its failure is measured by de Rham cohomology. Before discussing it, tackle integration of 2-forms.

To define integrals, often restrict class of functions or the domain of integration. (for line integrals, continuous functions on rectifiable curves). Here we (initially) restrict to functions on S with compact support \rightarrow means closure of $\{s \in S \mid f(s) \neq 0\}$ is compact.

S : oriented surface (automatic for Riemann surfaces - holomorphic charts are conformal)

- means that Jacobian taken to be positive at all points
det of matrix of first partials

If ρ : two-form = $R(x_1, x_2) dx_1 \wedge dx_2$ with $\text{supp}(\rho) \subset U$: open chart domain,
then $\int_S \rho = \int_{\mathbb{R}^2} R(x_1, x_2) dx_1 dx_2 \leftarrow$ Lebesgue integral.

Independent of local chart, even though Lebesgue integration doesn't see orientation, since change of vars is related by Jacobian which is positive.

What if $\text{supp}(\rho)$ is not in single chart? Here $\text{supp}(\rho)$ means write as $R(x_1, x_2) dx_1 dx_2$ in local coords with $R \neq 0$. The fact that $R \neq 0$ is independent of local chart. Use partition of unity - see previous notes...

Fact (General version of Green's/Stokes' theorem) $\int_{\partial S} \alpha = \int_S d\alpha$
 α : compactly supported 1-form on oriented surface S with boundary. Then:

If ρ doesn't have compact support, can define

$$\int_S \rho = \sup_{\chi} \int_S \chi \rho$$

This might be ∞ , of course.

where χ : any smooth compactly supported function on S taking values in $[0, 1]$.

Example of partition of unity: K : closed disk of radius $1/2$
 $U \subseteq \mathbb{R}^2$: open unit disk

Take $f(x_1, x_2) = F(\sqrt{x_1^2 + x_2^2})$ $F(r)$ any smooth function with $F(r) = 1$ for $r \leq 1/2$
 $F(r) = 0$ for $r \geq 3/4$

de Rham cohomology: Given the chain complex

$$\Omega_S^0 \xrightarrow{d} \Omega_S^1 \xrightarrow{d} \Omega_S^2 \quad \text{define}$$

for brevity, can use $d_i: \Omega_S^i \rightarrow \Omega_S^{i+1}$

$$H^0(S) = \ker(d: \Omega_S^0 \rightarrow \Omega_S^1)$$

$$H^1(S) = \ker(d: \Omega_S^1 \rightarrow \Omega_S^2) / \text{Im}(d: \Omega_S^0 \rightarrow \Omega_S^1)$$

$$H^2(S) = \Omega_S^2 / \text{Im}(d: \Omega_S^1 \rightarrow \Omega_S^2)$$

Examples: (*) If S connected, $H^0(S) = \mathbb{R}$ (both $\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2} = 0$ only if f constant)

(1) If $S = \mathbb{R}^2$, we showed $\ker(d_1) = \text{Im}(d_0)$

$$\text{so } H^1(\mathbb{R}^2) = 0.$$

Also $\Omega_S^2 = \text{Im}(d_1)$ since we need to find α_1, α_2 s.t.

$$\frac{\partial \alpha_1}{\partial x_2} - \frac{\partial \alpha_2}{\partial x_1} = R(x_1, x_2)$$

for local coords x_1, x_2 which can serve as global coords in $S = \mathbb{R}^2$.

$$\text{Take } \alpha_2 = 0 \text{ and } \alpha_1 = \int_0^{x_2} R(x_1, t) dt.$$

so $H^2(\mathbb{R}^2) = 0$ as well.

(Idea in general: use powerful theorems from integration theory (FTC, Stokes, etc) to easily compute cohomology groups.)

(2) If $S = S^2$, then write $S^2 = U \cup V$ two charts diffeomorphic to \mathbb{R}^2

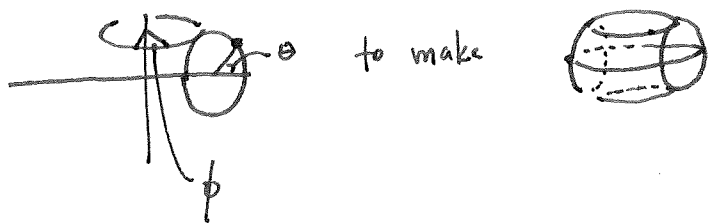
If α : 1-form on S^2 with $d\alpha = 0$, then writing $\alpha|_U$ for its restriction to $U \cong \mathbb{R}^2$, $\exists f_U$ s.t. $df_U = \alpha|_U$. Similarly $\exists f_V$.

On $U \cap V$, $d(f_U - f_V) = 0 \rightarrow f_U - f_V$ constant on $U \cap V$.

We can take this constant, c say, to be zero by changing say $f_U \mapsto f_U - c$ without affecting any of the above claims, regarding df_U . So $f_U = f_V$ on $U \cap V$

Thus ~~the~~ ^{the} f on S^2 equal to f_u on U , f_v on V , well-defined on all of S^2 , with $d = df$. $\Rightarrow H^1(S^2) = 0$.

(3) $S = T$: torus. Coordinatize with pair of angles $\theta, \phi \in [0, 2\pi)$



γ_1 : circle with $\theta = 0$
 $\phi \in [0, 2\pi)$

γ_2 : circle with $\phi = 0$
 $\theta \in [0, 2\pi)$

Consider the map on 1-forms:

$$\alpha \mapsto \left(\int_{\gamma_1} \alpha, \int_{\gamma_2} \alpha \right) \in \mathbb{R}^2. \quad (*)$$

Setting $\alpha = d\theta, d\phi$ shows the map is surjective. If f : smooth function on T

then $\int_{\gamma_i} df = 0$.

Thus map (*) induces map on $H^1(T) = \ker(d_1) / \text{Im}(d_0)$ to \mathbb{R}^2 .

claim: map is injective.

pf. of claim: if $\alpha = P d\theta + Q d\phi$ is closed 1-form such that

$$\int_{\gamma_2} \alpha = 0, \text{ then for any fixed } \phi, \int_0^{2\pi} P(\theta, \phi) d\theta = 0 \text{ by Stokes' thm.}$$

$\Rightarrow f(\theta, \phi) := \int_0^\theta P(u, \phi) du$ is smooth function on T with $\partial f / \partial \theta = P$

so $\tilde{\alpha} = \alpha - df$ is closed 1-form, which can be written as $\tilde{Q} d\phi$ for some \tilde{Q} .

But if $\tilde{\alpha}$ closed, then \tilde{Q} constant. So if $\int_{\gamma_1} \tilde{\alpha} = 0$, then $d = df$. //